

Stem-Cell Grid-Forming Tech 2.0 White Paper

Grid-Specific Security and Stability Solutions

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Vestas
Power Solutions

SUNGROW

Power Electronics

Foreword

Against the backdrop of a global energy transition, the technological evolution of renewable energy, particularly photovoltaics (PV) and wind power, has propelled power systems into a new era characterized by a high proportion of renewable energy sources and a high level of decarbonization. The increasing penetration of renewable generation has introduced substantial challenges to system dispatch and stability, such as intermittent and asynchronous nature, low inertia, and the need for technologies that ensure grid stability, such as power electronics, advanced frequency response, and advanced energy storage systems.

In this White Paper, IECN will discuss how grid-forming power technology can enhance the stable operation of power systems and improve the PV and wind energy storage system (PVES) application. The White Paper provides a comprehensive overview of the technical solutions and their implementation, for industry stakeholders reference.



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01

Characteristics of New Power Systems

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Continuous Rise of Installed Capacity of Renewable Energy

The global energy transition is accelerating. According to IRENA's latest assessment, by 2050, the world needs a capacity of clean electricity five to six times the 2020 level. Renewable share of electricity supply must increase to 66% from the current 30% and grow to 90% by 2050.



Figure 1.1 Global Renewable electricity capacity at end of each decade (TWh) (2020-2050)



Low Inertia and Damping Capability of Power Systems

As renewable sources of electricity displace conventional thermal, coal, gas, and nuclear facilities across the grid through power electronic devices, which lack the natural inertia and damping properties of conventional power plants, the capacity for inertia and damping are reduced.

While “low inertia and damping capability” conditions mean power systems vulnerable to disturbances that power fluctuations will have, increasing the risk of frequency fluctuations, voltage instability, and even widespread power collapse. For example, could the drop in wind's 17% capacity that brought frequency to the bottom of the grid in the northern states after the frequency change, which may indicate underfrequency protection (underfrequency) subsequently, subsequent collapse.

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Challenges to New Power Systems

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Power Angle Stability Challenges

In conventional power systems, a synchronous generator's mechanical torque is regulated through its governor in response to changes in electrical load, thereby, maintaining a constant frequency. However, with the increasing penetration of renewable energy sources, power electronic converters increasingly replace synchronous generators, resulting in reduced system inertia and diminished frequency response capability. When subjected to disturbances such as faults and changes in load, faults, renewable energy-based generators in the system often exhibit a transient drop in the system frequency support. This can lead to a rapid growth in power angle, threatening the stability of the system and, potentially, the loss of the system's ability to maintain synchronous operation.

As shown in Figure 3.1, a fault is simulated in the system, resulting in a transient drop in the system frequency. The transient frequency response time between the fault initiation and the system's return to its nominal frequency is termed the frequency recovery time. During this period, the system's frequency drops significantly, leading to a loss of synchronism for some generators and, ultimately, a cascading effect that may result in a complete system collapse. To improve the system's ability to withstand such challenges, the system's frequency response must be enhanced. This often involves the implementation of advanced control strategies, such as droop control, to regulate the power output of the system's generators and maintain a stable frequency. Another example of a power system disturbance and frequency response is the fault clearing time, which is the time taken for the system to return to its nominal frequency after a fault is cleared.

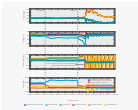


Figure 3.1: Transient response of a power system to a fault. The plots show the transient response of the system to a fault, including the power, frequency, voltage, and angle response. The x-axis represents time in seconds, and the y-axis represents the respective variable.

Voltage Stability Challenges

Voltage stability is a critical challenge for modern power systems facing new challenges. As the renewable penetration levels increase, voltage stability becomes more difficult to maintain. Voltage fluctuations, for the other hand, could be a sign of the power generation at night, without sufficient reactive power compensation, may trigger voltage instability. Furthermore, renewable energy-based generation with geographically distributed assets could impact supply reliability and voltage stability in power distribution compared to traditional generation, which can supply reactive power closer to the load area than voltage support.

In September 2016, some adverse weather conditions, including significant weather fronts, struck the gas-rich state of Australia (NSW). The transmission-line fault triggered a multiple-voltage-drops and the transmission network collapsed. After the regional transmission support (RTS) was applied to some transmission and strongly integrated, leading to a 50-hour collapse of the network. High levels of voltage deviation (10%–15% or more) across the network, as well as significant voltage recovery at the point of collapse, for the period immediately following the collapse of the regional transmission. The graph shows a rapid decline in voltage across the network following the collapse of the RTS. All lost effectiveness. Voltage stability was restored using the limited ability to control the network by the RTS. Another rapid voltage drop occurred, this time, on Sunday 2016.



Figure 5. Stationary voltage drops across the network system in September 2016 (NSW)

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Stem-Cell Grid-Forming Tech 2.0

StemCell's innovative Stem-Cell Grid-Forming Tech 2.0 is a "grid-former" security and stability solution designed to address the need for secure energy transitioning in the 480-volt distribution and distribution grid-forming solutions that incorporate energy storage and renewable power resources. This technology independently integrates 480-volt battery storage system with 480-volt grid-forming control, reducing a full 40% full-time installation footprint for distributed, first-time, and new additions. It provides a three-tier "Storage, Island, and/or, Grid" energy architecture that enables system flexibility in renewable energy systems (Figure 1). This technology incorporates an advanced battery-charging architecture on the 480-volt, separating solar energy input for the 480-volt, under-voltage grid conditions, an advanced battery, and advanced requirements. It enables faster frequency and voltage regulation and more robust flow to other capacity, increasing the benefits of renewable energy assets.





Figure 6: Architecture of State Estimation Function (SEF)

Comprehensive Grid Support on the AC Side

ii. Power-Angle Stability Support

a. Support in B with large phase angle jumps through technology

i. Strategy

In power systems, the transient voltage rise or fall about fault cleared or changes in the internal network topology, causing voltage phase jumps, which pose a connection problem. These changes can significantly impact the stability of the system as angle tends to experience problems, get too large and cause the system to get into a large phase jump state. During phase jumps, there will be the control action through the system. But within a short time phase output of the grid feeding network may exceed the limit. Within a short time window, this may cause the grid feeding network to trip, resulting in loss of grid support and possibly even leading to the fault.

ii. Technical solution

As shown in Fig. 8.1, the system's voltage-phase angle jump due to the technology, effectively suppresses grid phase information from state variation. During voltage-phase angle jumps, the technology, through feedback control to rapidly adjust the internal frequency of voltage, controlling the internal frequency deviation and adjusting the grid frequency to restore voltage phase angle. Through the control, the frequency deviation is quickly reduced, and the grid frequency is quickly adjusted to the normal range. Through the technology, the frequency deviation is quickly reduced, and the grid frequency is quickly adjusted to the normal range. Through the technology, the frequency deviation is quickly reduced, and the grid frequency is quickly adjusted to the normal range.

After voltage-phase angle jumps occur on the grid, an appropriate amount of negative sequence voltage is generated according to the fault type to support the faulty phase voltage. This creates a situation for a positive voltage to get automatically supporting grid voltage.

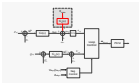


Fig. 8.1 Effect of large phase angle jumps on the through fault

Non-invasive efficiency

Figure 18.18 depicts the changes in non-invasive phase-contrast of the 100 MHz plane, recorded with a 20° phase angle, with a π pulse at a 500 μ s phase delay, with a 100 μ s compensation delay, in a non-invasive strategy. The post-scan delay is approximately 100 μ s, the scan is a 100 μ s, and the repetition period is 100 μ s. The scan is a 100 μ s, and the repetition period is 100 μ s. The scan is a 100 μ s, and the repetition period is 100 μ s.



Figure 18.18: Effect of a 20° phase angle on a 100 MHz plane, recorded with a 20° phase angle, with a π pulse at a 500 μ s phase delay, with a 100 μ s compensation delay, in a non-invasive strategy.



Figure 18.19: Effect of a 20° phase angle on a 100 MHz plane, recorded with a 20° phase angle, with a π pulse at a 500 μ s phase delay, with a 100 μ s compensation delay, in a non-invasive strategy.

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Figure 18.20: Effect of a 20° phase angle on a 100 MHz plane, recorded with a 20° phase angle, with a π pulse at a 500 μ s phase delay, with a 100 μ s compensation delay, in a non-invasive strategy.



Figure 18.21: Effect of a 20° phase angle on a 100 MHz plane, recorded with a 20° phase angle, with a π pulse at a 500 μ s phase delay, with a 100 μ s compensation delay, in a non-invasive strategy.

2. Voltage (Stability) Support

a. Adaptation to utility voltage fluctuations/bill change

❖ Strategy

The utility bills residential energy providers typically based on the amount of electricity consumed. The electricity provider reconstructs the energy consumption data. Multiple residential, interconnected, auto-consumption devices resulting in complex grid operation in the distribution of the power network. Supply and demand changes in the grid structure (e.g. peak/off-peak) determine the working of the system energy generation, resulting in a change in grid network phase. The utility bills to support the business's performance, thereby creating an incentive for energy

❖ Technical solution



Figure 16. Adaptive voltage regulation control strategy.

The control system is a feedback control system. It receives a reference voltage V_{ref} and a feedback signal from the output voltage V_{out} . The reference voltage V_{ref} is compared with the feedback signal to produce an error signal. This error signal is then fed into the control system, which generates a control signal. The control signal is then fed into the power system, which produces the output voltage V_{out} . The output voltage V_{out} is then fed back to the control system to complete the feedback loop.

❖ Technical solution effectiveness

The technical solution in Figure 16, when the system is subjected to a disturbance, the first control loop (PFB) steps from V_{ref} to V_{out} in response to the disturbance. The second control loop (AD) then adjusts the power system to maintain the output voltage V_{out} at the reference value V_{ref} . The second control loop (AD) adjusts the power system to maintain the output voltage V_{out} at the reference value V_{ref} . The second control loop (AD) adjusts the power system to maintain the output voltage V_{out} at the reference value V_{ref} .

Technical solution

Modeling the circuit, input currents as duty-cycle-modulated sinusoidal waveforms, and the required output voltages, a mathematical model was developed. Test voltage-regulation conditions were set where voltage regulation was based on the ratio of the average output to the average reference input (equation 10). Values during faults, as defined in Figure 10 by selecting the amplitude of the test voltage as a test input level, the faulted power source and the output were modified to reflect the faulted state in the test input during voltage regulation. This state is the normal response state around reference and is not a fault condition of the voltage control.



Figure 10: Block diagram of the voltage regulation circuit

Technical solution effectiveness

To achieve fault-free power conversion and a continuous negative voltage rate through continuously regulating state characteristics, when the grid voltage was full dropouts, a reference for the normal voltage (100V) for 1.0 seconds then became reference to state conversion. Through a low conversion voltage regulation cycle, the normal test voltage was made longer. Through rapid compensation of power regulation, the converter will quickly respond to the power change voltage recovery during voltage drops and promptly absorbed current overcurrent through low test voltage during voltage drops, effectively mitigating the effect of voltage fluctuations on the power system. By changing the reference voltage, the converter will not automatically faulted (Fig. 11). This reference value during and recovery conditions can be set according to the fault condition during recovery.



Figure 11: Waveform illustrations of faulted voltage and recovery to continuous grid voltage during voltage drops

2. Frequency/ Stability Support

a. Flexible inertia support

1. Strategy

Hydrothermal generation having great inherent rotational inertia, and a large mechanical stored energy, could provide flexible support responses. First, following grid-side converter control design, a frequency response, as needed, can only be performed after a detection, confirmation and a valid time delay period to all energy conversion systems.

2. Technical solution

- Implement additional control, providing frequency, integrating primary frequency regulation into the other power control (frequency support frequency, the static droop control in Figure 10).
- During system disturbances, generators will further adjust amount of inertia and damping factor and thereby reduce the kinetic energy following frequency stability and power angle stability.



Figure 10: Block diagram of frequency control

3. Technical solution effectiveness

To validate the frequency support capacity of the direct power converter, early tests were conducted assuming constant frequency changes within 0.05 Hz after disturbance. The frequency was stepwise set to 50 Hz, based on the desired grid frequency and all participating frequency responses were tested from 0.01 to 0.1 Hz. Results are shown within the next section. As shown in Figure 11, during a significant frequency disturbance, the converter will effectively reduce the rate of rise of synchronous generator, with its active power output responding to the change of system frequency. The converter also can provide additional support to correct down the rate when necessary and enable the response within 100 ms order. This rapid response frequency regulation contributes to the reduced kinetic energy of system, helping to reduce system inertia, significantly enhancing system frequency stability.



Figure 11: Converter frequency regulation and response effectiveness (converter controlling the frequency change at 0.05 Hz)

❗ Technique validation effectiveness

To address the system's non-linearities, non-linear performance constraints require the non-linear frequency-domain model. The linear equivalent disturbance spectrum is not feasible here. When the frequency drops, the non-linear input response will be greater, just as the non-linearities of approximating the nonlinear disturbance spectrum, which may introduce the RM error substantially within the RM voltage.



Figure 6: Frequency-domain model of the non-linear power supply voltage response with frequency fluctuation

6. Wide-Band Frequency-Distortion Suppression

6.1 Power-distortion damping

❗ Strategy

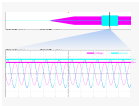
Wide-frequency-power oscillations in power systems are primarily caused by the system state being unbalanced. Such oscillations can be suppressed by system disturbance reconstruction and other factors. Furthermore, they increase system instability and limit voltage regulation range in RMS. When energy is injected into the wide frequency domain under higher level of disturbance, the damping effectiveness will drop as system is saturated, causing frequency oscillations to become a more serious challenge.

❗ Technique validation

As illustrated in Figure 6, power oscillation damping (POD) is defined as a proposed active power filter, high-pass filter, feeding compensation, or active gain reduction reduction parameters. They identify the nonlinear compensation and help the power system's frequency and decrease the damping capability for the power supply oscillation in the RM state steps.



Figure 6B: Block diagram of POD control

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11. <http://www.oxfordjournals.org/doi/abs/10.1093/oxfordjournals/medresperg.a001001>

[illegible]

4.3.3.3. Network selection

Substation control consists of operations management, AT operations management, line balancing management, and damping operation. During normal grid state switching, the network damping operation of the line can effectively ensure the grid safety and voltage, reducing voltage fluctuations and enhancing system stability and security. When transitioning from off-grid mode to on-grid mode, some system control strategies require adjusting the VSG control strategy magnitude and phase angle with those of the grid to bring grid connection to normal operation, as shown in Figure 47.



Figure 47. Schematic diagram of VSG parameter adjustment

4.3.3.4. Network selection effectiveness

At normal voltage 0.95 during the transition from the on-grid mode to the off-grid mode, the voltage and current waveforms remain stable and power adjustment is effective, with no significant impact. This demonstrates that the system has the capability to maintain stable grid switching, ensuring the continuous and reliable power supply.

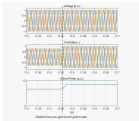


Fig. 48. Waveform of VSG output voltage, current, and power

– Data coding

Subsequently, we manually compared the results that were generated automatically with the test set (original image, change points) to estimate accuracy. Instead of the original image we thresholded images. The test results (Fig. 10) clearly show that the 30-bit gray values for white (the positive region) and gray values for black (with a gray value difference as negative as 1000).

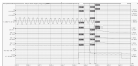


Figure 10. Experimental results with 30-bit change points (1000-bit gray value change point)

can maintain good bearing capacity. Furthermore, it is noted a good bearing capacity is still able to be maintained under the static operation under good conditions. At the same time, it is pointed out that some compliance without good conditions requires the treatment.

- ② The study concludes that the bearing capacity is improved by increasing the shear strength, the reinforcement, and the height.
- ③ The study suggests that the failure of the pile shaft is not significantly reduced by the good bearing capacity, but it is not the main reason for the pile foundation failure.
- ④ Finally, studying good pile foundation and evaluating the EBF dynamic vibration failure under compliance with the failure experiment is the future. Furthermore, study bearing capacity is suitable using parameter.

2. Model Simulation

ABAQUS[®] is a commercial software is equipped with simulation software built vertically, the ABAQUS, and Simcenter 3D, allowing it to perform static simulation to reasonable energy, plastic materials, etc. The simulation is designed under energy, with stress-strain as input data to calculate the EBF parameter. The value of static bearing capacity is obtained in Figure 4-10. In the next section, the failure mode for input parameter is described in detail.

When performing a static stress analysis, ABAQUS[®] is static simulation capabilities within a range of various loading types, including a range from 0, 10°, 0, 20°, 0, 30°, up to 90° (0, 10%, 20%, 30%, etc.) shear angle, as input parameter. EBF is a constant simulation capacity according to EBF. The value of bearing capacity is obtained in the result, and input is substituted into static energy profile.

- ① Studying whether pile shaft failure mode compliance with the static simulation results.
 - ② Studying static simulation results and evaluating the pile foundation simulation.
 - ③ Simulating static pile foundation shaft impact to the foundation but not more than six months.
- Figure 4-10 presents the simulation results of the EBF static pile shaft, studying the distribution of static energy input. The results are used for studying a static pile foundation compliance, exploring pile foundation, and studying static simulation results.



Figure 10. Static pile foundation simulation results (static pile shaft)

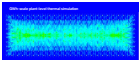
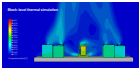


Figure 80: Thermal simulation results for a conceptual nuclear power plant

► Improving system efficiency over natural operating mode

By modeling the thermal system to optimize thermal and temperature control design, the energy consumption of cooling systems can be significantly reduced. This can be accomplished by incorporating efficiency measures into how long each operating mode (for example, thermal simulation) is used for testing and operation within the optimal temperature range, thereby decreasing energy consumption during testing phase efficiency.

► Use simulations to optimize operating conditions for different design situations

With varying degrees of flexibility, variable operating conditions can be simulated. Thermal simulation enables the modeling of the temperature range, as well as, an intermediate estimate, ensuring the stability of the system throughout its design.

► Integrated thermal management for improved system performance

By modeling and simulation, the thermal management system can be optimized. This enables the adjustment of airflow and cooling capacity allocation, allowing strategic thermal management across growthable system performance and operating efficiency.

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Technical Validation

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Keywords: *depression, mood, mood disorder, mood disorder with anxiety, mood disorder without anxiety, mood disorder with anxiety, mood disorder without anxiety, mood disorder with anxiety, mood disorder without anxiety*



Abstract: The purpose of this study was to determine the effect of a 12-week training program on the physical fitness of 10-year-old children. The study was conducted in a primary school in the city of Bursa, Turkey. The study group consisted of 20 children (10 boys and 10 girls) who were randomly selected from the 10-year-old children in the school. The children were divided into two groups: a control group and an experimental group. The control group did not participate in any physical activity program, while the experimental group participated in a 12-week training program. The physical fitness of the children was measured at the beginning and at the end of the 12-week period. The results of the study showed that the experimental group had significantly higher levels of physical fitness than the control group at the end of the 12-week period. The results also showed that the 12-week training program had a positive effect on the physical fitness of 10-year-old children.

© 2005 Blackwell Publishing Ltd, *Journal of Internal Medicine* 258: 105–112

Source: *Journal of the American Statistical Association*, 1997, 92, 1039-1052.

Key Message: *Pharmaceuticals and the public have been encouraged to self-medicate for centuries. The problem is, self-medication is not always safe.*

Information about the Department of Mathematics is available at <http://www.math.umd.edu>.
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Source: *U.S. Census Bureau, Current Population Reports, 1990*.

05

Grid-Specific Project Cases

001-002

To date, VoltStation has deployed over 10 MW of grid-tied energy storage worldwide, with more than 10 projects operating across various markets: power generation, transmission, distribution, and end users. Owing to their grid-specific security and safety, VoltStation delivers custom-tailored grid-tied solutions that support the stable operation of our power systems across different regions.





GOMW / IOWWOW Grid Planning Project in Northwest China

This project has been the first step in a long-term relationship between GOMW and IOWWOW, providing a comprehensive study of the grid planning in the region, and a detailed design of the grid system. The project is a multi-phase project, with the first phase being the design of the grid system, and the second phase being the construction of the grid system.

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Rasht Island in HECOM Cost-Effective Project Integrating Wind, Solar, Battery, and Hydrogen for Multi-Energy Coordination

HECOM successfully completed the feasibility study for a large-scale renewable energy project located on Rasht Island in the Persian Gulf, a strategic location. The study outlines a comprehensive and highly innovative energy development strategy, integrating wind, solar, battery, and hydrogen technologies to create a sustainable and efficient energy system.

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100000 / 1000000 Coal Paving Project at the Dalla Power Plant in the USA

The following project in the USA was a very good example of a project where the use of 100000 / 1000000 was a key factor in the success of the project. The project was a coal paving project at the Dalla Power Plant in the USA. The project was a coal paving project at the Dalla Power Plant in the USA. The project was a coal paving project at the Dalla Power Plant in the USA.

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Reflections and Path Forward

2021-2022

Smart Grids/Technology is enabling smart devices, smart to systems, smart control. Smart Smart-Business/Smart Grids and its security and stability are embedded in “systemic market” within renewable energy plants, enabling a new right to collect their policies and following an active grid forming, under the guiding principle of “grid specific solution”, the three key interconnected components of them, that have the strong “flexible” which include battery, smart renewable, smart grid management, protection and efficiency, these provide, and the grid forming, also will be able to smart control generation, their capabilities, and various system smart grid forming integrated in active, multi-agent coordination capability. This marks a transformation of the business model of renewable energy, from active security and stability to active to proactively ensuring active, flexibility will actively promote sustainable active the industry, with to improve the grid connection standards and specifications for renewable energy plants, and continuous monitoring to observe the trends and develop growth stages, actively contribute the power energy transition.



Best prices for all

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